

## Lecture 2

### I. The error estimate for the Euler explicit method applied to the initial value problem

Exact problem

$$(1) \quad \begin{cases} y' = f(t, y) \\ y(t_0) = y_0 \end{cases}$$

Assumptions:

1. the function  $f(t, y)$  is regular (i.e. it has continuous derivatives  $f_t(t, y)$ ,  $f_y(t, y)$ ,  $f_{tt}(t, y)$ ,  $f_{ty}(t, y)$ ,  $f_{yy}(t, y)$ ), in particular it satisfies the Lipschitz condition

$$|f(t, y_1) - f(t, y_2)| \leq L|y_1 - y_2|$$

for all  $t, y_1, y_2$ , where  $L > 0$  is some constant.

2. let

$$M = \max_{(t,y)} \{|f(t, y)|, |f_t(t, y)|, |f_x(t, y)|, |f_{tt}(t, y)|, |f_{xt}(t, y)|, |f_{xx}(t, y)|\}$$

We define the approximate problem as follows:

Find a series of approximate values using the explicit Euler algorithm

$$y_0, \quad y_{i+1} = y_i + hf(t_i, y_i), \quad i = 0, 1, 2, \dots, n - 1$$

The global error of approximation is defined as follows

$$e(h) = \max_{1 \leq i \leq n} |y(t_i) - y_i|.$$

To analyze  $e(h)$  we consider the sequence of the errors at the individual grid points

$$e_i = y(t_i) - y_i, \quad i = 1, 2, \dots, n,$$

Then by Taylor's formula\* (up to the first term) we get

$$(2) \quad y(t_{i+1}) = y(t_i) + hy'(t_i) + R(h),$$

$$\text{where } |R(h)| \leq Ch^2,$$

$$C = \frac{1}{2} \max_{t_i \leq t \leq t_{i+1}} |y''(t)| = \frac{1}{2} \max_{t_i \leq t \leq t_{i+1}} |f_t + f \cdot f_y| \leq \frac{1}{2}(M + M^2) \leq M^2$$

$$y'' = (y')' = \frac{d}{dt}f(t, y) = f_t(t, y) + y'f_y(t, y) = f_t + f \cdot f_y$$

It follows from the differential equations that  $y'(t_i) = f(t_i, y_i)$ , therefore

$$(3) \quad y(t_{i+1}) = y(t_i) + hf(t_i, y_i) + R(h)$$

\* - Taylor's formula up to  $n - th$  term has a form:

$$y(t+h) = y(t) + \frac{h}{1!}y'(t) + \frac{h^2}{2!}y''(t) + \dots + \frac{h^n}{n!}y^{(n)}(t) + R_n(h),$$

where  $R_n(h)$  is the remainder, for which we have an estimate  $|R_n(h)| \leq Ch^{n+1}$ .

Since

$$(4) \quad y_{i+1} = y_i + hf(t_i, y_i),$$

it follows from (??) and (??) that

$$(5) \quad e_{i+1} = y(t_{i+1}) - y_{i+1} = (y(t_i) - y_i) + h(f(t_i, y(t_i)) - f(t_i, y_i)) + R(h).$$

Since  $f$  satisfies the Lipschitz condition

$$|f(t_i, y(t_i)) - f(t_i, y_i)| \leq L|y(t_i) - y_i|,$$

from (??) we get inequality

$$(6) \quad |e_{i+1}| \leq (1 + Lh)|e_i| + Ch^2, \quad i = 0, 1, 2, \dots, n,$$

where  $C > 0$  is some constant independent of  $h$ . We discuss this inequality beginning with the following auxilliary lemma

Lemma 1.

Let the sequence  $\{e_i\}$  satisfy

$$(7) \quad |e_{i+1}| \leq A|e_i| + B, \quad i = 0, 1, 2, \dots$$

where  $A, B > 0$  are some constants. Then for each  $e_i$  we have the following explicit estimate

$$(8) \quad |e_i| \leq A^i|e_0| + B \frac{A^i - 1}{A - 1}, \quad i = 0, 1, 2, \dots$$

Proof of lemma. The proof is by induction. First we observe that

$$|e_1| \leq A|e_0| + B.$$

Assuming (??) for  $i$ , for  $i + 1$  we get inequality

$$|e_{i+1}| \leq A|e_i| + B \leq A \left( A^i |e_0| + B \frac{A^i - 1}{A - 1} \right) + B = A^{i+1} |e_0| + B \frac{A^{i+1} - 1}{A - 1}.$$

An inductive argument ends the proof.

Now we apply lemma 1 to our sequence, where  $e_0 = 0$ ,  $A = 1 + Lh$  and  $B = Ch^2$ . Then we get

$$e_i \leq \frac{(1 + hL)^i - 1}{hL} Ch^2 \leq \frac{C}{L} (1 + hL)^n h, \quad 0 \leq i \leq n.$$

Since

$$t_0 < t_1 < \dots < t_n = T, \quad nh = T - t_0$$

we have

$$(1 + hL)^n = \left[ (1 + hL)^{\frac{1}{hL}} \right]^{nhL} \leq \exp((T - t_0)L),$$

The last inequality follows from the known inequality  $(1 + x)^{\frac{1}{x}} \leq e$  for  $x > 0$ . Finally we get the estimate of the global error for the explicit Euler method

$$(9) \quad e(h) = \max_{0 \leq i \leq n} |e_i(h)| \leq \frac{C}{L} e^{(T-t_0)L} h = C_1 h.$$

Let us compare the global error (??) for the explicit Euler method with the local error. For the latter error we have an estimate

$$(10) \quad e_l^i(h) = |y(t_{i+1}) - y(t_i) - hf(t_i, y(t_i))| = |y(t_{i+1}) - y(t_i) - hy'(t_i)| = |r(h)|$$

where  $r(h)$  is the remainder in Taylor's formula, which satisfies the inequality  $|r(h)| \leq Ch^2$ . Hence it follows that

$$e_l(h) = \max_{0 \leq i \leq n} (e_l^i(h)) \leq Ch^2.$$

Generally, for difference methods between local and global errors we usually have the following relation

$$(11) \quad e_i(h) \leq ch^{p+1} \text{ and } e(h) \leq ch^p,$$

where  $p > 0$  is the order of the method.

### III Practical methods of higher order - the Runge-Kutta's methods

1. The method of the second order

$$\begin{aligned} y_{i+1} : \quad k_1 &= f(t_i, y_i)h \\ k_2 &= f\left(t_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1h\right)h \\ y_{i+1} &= y_i + k_2 \end{aligned}$$

2. The method of the fourth order

$$\begin{aligned} y_{i+1} : \quad k_1 &= f(t_i, y_i)h \\ k_2 &= f\left(t_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1h\right)h \end{aligned}$$

$$\begin{aligned} k_3 &= f\left(t_i + \frac{1}{2}h, y_i + \frac{1}{2}k_2h\right)h \\ k_4 &= f(t_i + h, y_i + k_3h)h \\ y_{i+1} &= y_i + \frac{1}{6}k_1 + \frac{1}{3}k_2 + \frac{1}{3}k_3 + \frac{1}{6}k_4 \end{aligned}$$

**Example 1.** The second order Runge-Kutta method for the system of equations

$$\begin{cases} x' = f(t, x, y) \\ y' = g(t, x, y) \end{cases}$$

$$\begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix} : k_1 = \begin{bmatrix} k_{11} \\ k_{12} \end{bmatrix} = \begin{bmatrix} f(t_i, x_i, y_i)h \\ g(t_i, x_i, y_i)h \end{bmatrix}$$

$$k_2 = \begin{bmatrix} k_{21} \\ k_{22} \end{bmatrix} = \begin{bmatrix} f(t_i + \frac{1}{2}h, x_i + \frac{1}{2}k_{11}, y_i + \frac{1}{2}k_{12})h \\ g(t_i + \frac{1}{2}h, x_i + \frac{1}{2}k_{11}, y_i + \frac{1}{2}k_{12})h \end{bmatrix}$$

$$\begin{bmatrix} x_{i+1} \\ y_{i+1} \end{bmatrix} = \begin{bmatrix} x_i \\ y_i \end{bmatrix} + \begin{bmatrix} k_{21} \\ k_{22} \end{bmatrix}$$

A practical guide for verification of the order  $p > 0$  in (??) of the convergence rate of the algorithm.

1. Assume that  $e(h) \approx Ch^p$ .
2. Let choose a step  $h_0$  for example  $h_0 = 0.05$  and perform numerical tests for a number of step sizes of  $h$ , for example  $h = h_0, h_0/2, h_0/4, \dots, h_0/2^5$ .
3. For each value of  $h$ , determine errors:  $e(h_0), e(h_0/2), e(h_0/4), \dots, e(h_0/2^5)$  of the approximation of the exact solution  $y(t)$  by an approximate solution  $y_h$ .
4. If in point 3. the exact solution  $y(t)$  is not available, you can take instead the approximate solution  $y_h$  obtained for the last value of step  $h$ .
5. It follows from our assumption that

$$e(h_0) \approx Ch_0^p, \quad e(h_0/2) \approx Ch_0^p 2^{-p}, \quad e(h_0/4) \approx C 2^{-2p} h_0^p, \quad \dots$$

$$e(h_0/2^k) \approx C 2^{-kp} h_0^p,$$

So we may expect that

$$e(h_0/2^i)/e(h_0/2^{i+1}) \approx 2^p, \quad i = 0, 1, 2, \dots,$$

which is verifiable by computation. Hence we retrieve the value of  $p$ .

6. To illustrate results you can draw the points

$$P_k = (-\ln(h_0/2^k), -\ln(e(h_0/2^k))).$$

Since

$$-\ln(e(h)) \approx p \ln(-h) + \ln(-C),$$

we expect that points  $P_k$  are arranged along the line  $y = p \cdot x + b$ . The coefficients  $p$  and  $b$  can be retrieved by using a Matlab command 'polyfit'.